

## IN THE SPECIFICATION

### DETAILED DESCRIPTION OF THE INVENTION

Replace the first paragraph at page 10 with the following paragraph:

A<sub>1</sub> In Fig.1 a hand guided electrical tool embodying the invention, in particular a drill, is represented comprised of a housing 1 and a guide part 2 for holding a drive shaft 3. A spade-shaped auxiliary handle generally designated by 5 is secured on the electrical tool by means of a sleeve-like locking ring 4 enclosing the guide part 2, whereby the locking ring 4 extends in the axial direction of the drive shaft 3. The locking ring 4 is pivotable around an axis of rotation parallel to the drive shaft and can be secured in different positions. The locking ring 4 is arranged at one corner of the spade-shaped auxiliary handle 5 formed radially outwardly by two radially outwardly emerging arms 14a diverging outwardly to terminating at a cross arm 14b.

Replace the first paragraph at page 11 with the following paragraph:

A<sub>2</sub> In Figs. 2 to 5 a first embodiment of a locking ring 10 with an actuation element 16 is shown. The locking ring 10 has a coaxially arranged clamping ring 12 that is rotatable relative to the locking ring. The clamping ring 12 includes at least one clamping tongue 13 that can be brought into contact with a guide part 11 as is represented in particular in Fig. 4. The clamping tongue 13, in particular the clamping ring 12, is secured by rotation relative to ~~an~~ the auxiliary handle 14 into a

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locked position at the guide part 11 as is displayed in particular in Fig. 5. In its radial projection region the clamping tongue 13 and the locking element 10 cooperate by way of the clamping pads 15. As a result of rotation in the setting direction F, the clamping pads 15 urge the two diametrically arranged clamping tongues 13 against the guide part 11 and thus secure the auxiliary handle 14 in a friction locked manner to the guide part 11. Release of the connection is obtained by rotation opposite to the setting direction F, as shown particularly in Fig. 3. Particularly in Fig. 4, the clamping ring 12 is represented together with the actuation element 16.

The auxiliary handle 5, 14 is triangularly shaped in a plane extending transversely of the axis of the drive shaft 3 with its two arms 14a extending radially outwardly from the locking ring 10. The arms 14a are in a radially outward diverging relationship and terminate at the opposite ends of the cross arm 14b.

Replace the second paragraph at page 12, line 11 to page 13 line 4, with the following paragraph:

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A fourth embodiment is represented in Fig. 14. A guide part 30 is surrounded on its circumference by a retention band 31. A loop 32 of the retention band 31 is passed through a slit 33 in a locking ring 34 surrounding the guide part 30 and the retention band 31. A clamping bolt 35 running parallel to the axis of the guide part 30 passes through the loop 32 of the retention band 31. The clamping

Q3 bolt 35 is arranged at one end 37 of an actuation element 36 and perpendicular to it. The end 37 has a circular cross-section running eccentrically to the clamping bolt 35 and is rotationally mounted in a complementary recess in the locking ring 34. By virtue of the eccentric arrangement of the clamping ~~bolt~~ bolt 35, the retainer band 31 encircling the guide part 30 is tightened by the pivoting of the actuation element 36 in a setting direction F and therewith secures the guide part 30 relative to the locking ring 34 which is fixed to an auxiliary handle 38. By pivoting in a direction opposite to that of the setting direction F the retainer band 31 is again loosened and the guide part 30 thus released again.

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